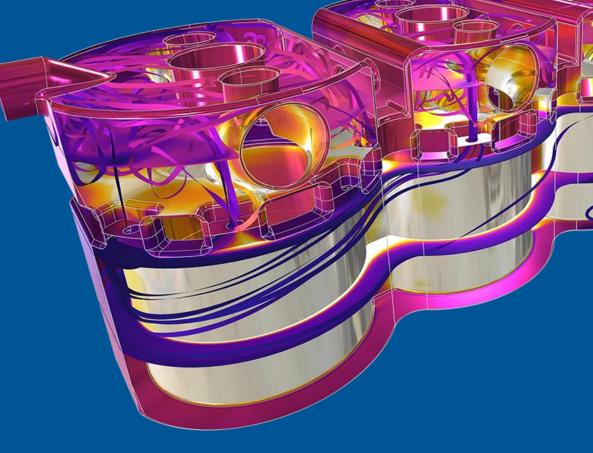
Setting up a Deep Neural Network for Structural-Thermal-Optical Model



Tomáš Vrbata vrbata@humusoft.cz

Schedule

- 1. Deep Neural Networks (DNN)
- 2. STOP Analysis
- 3. Demo Model Description
- 4. Demo How to Create Surrogate model for STOP Analysis
- 5. Conclusions

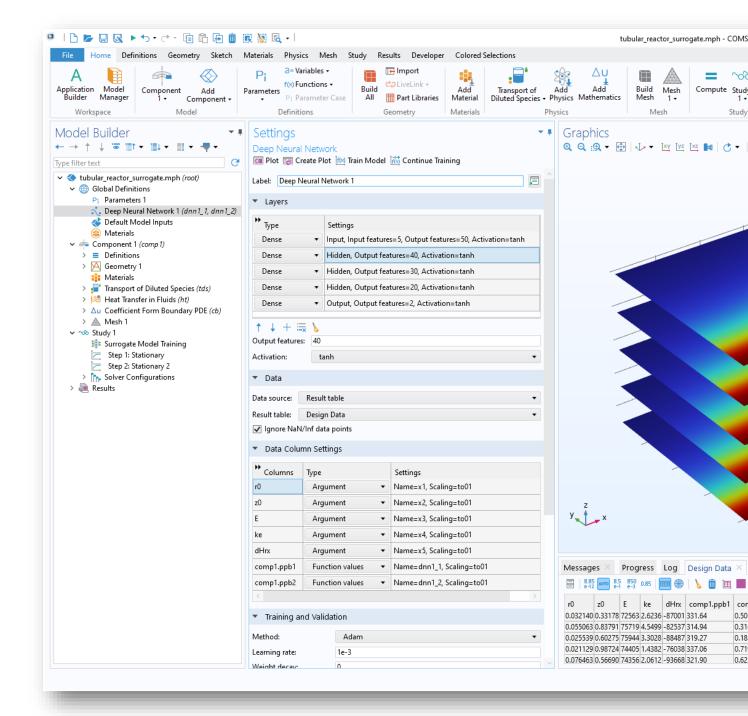


Deep Neural Networks (DNN) in COMSOL Multiphysics

Tomáš Vrbata

New Powerful Functionality

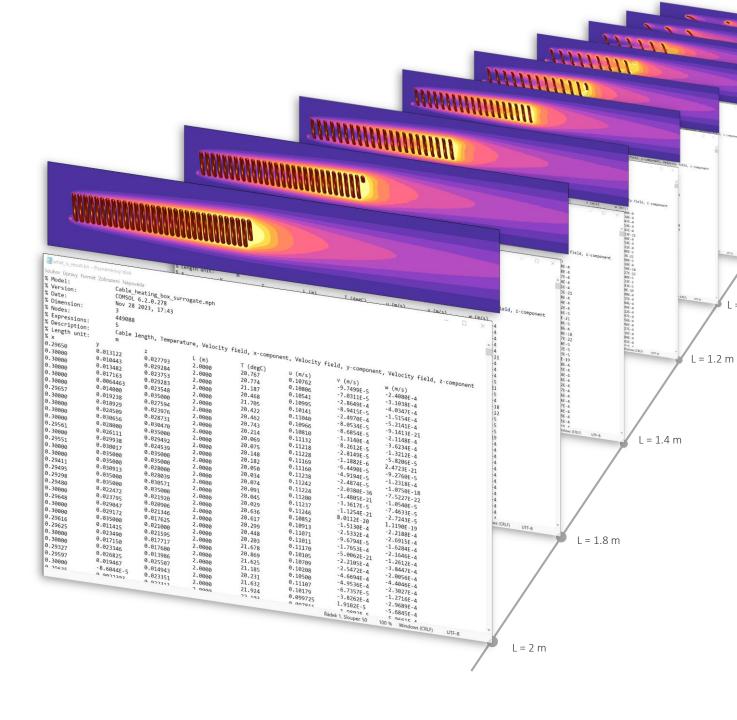
- DNN is a new type of function
- General multidimensional function interpolation and approximation
- Requires a training data table



New Powerful Functionality

 The original parametrized 3D FEM model can be viewed as a set of large tables:

x, y, z, parameters, computed quantities

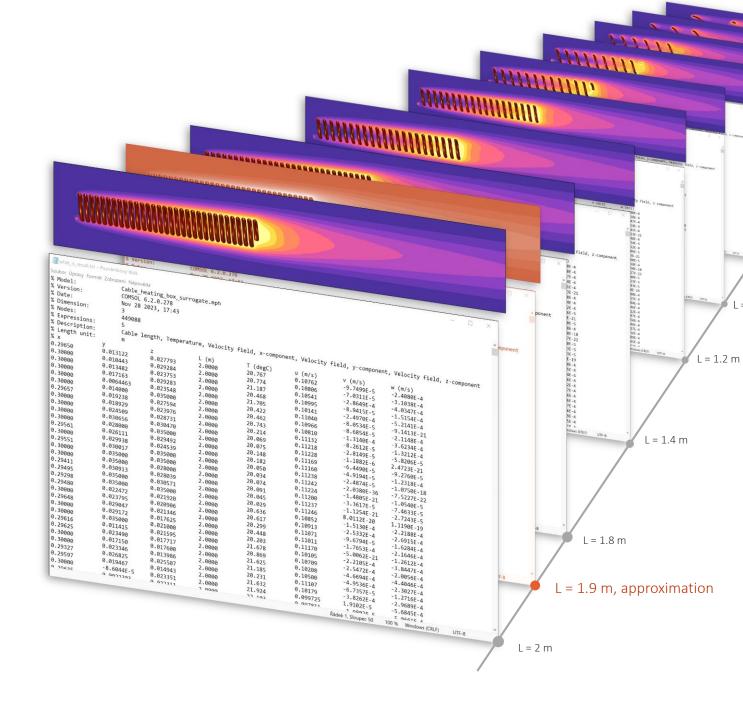


New Powerful Functionality

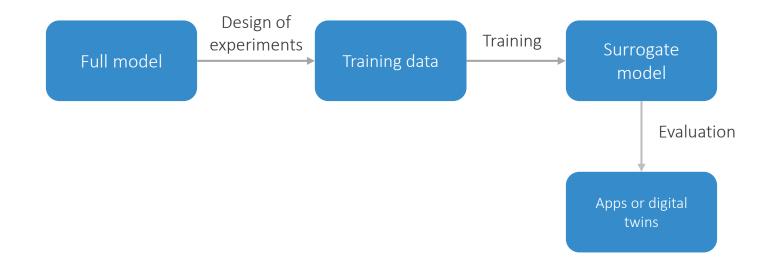
 The original parametrized 3D FEM model can be viewed as a set of large tables:

x, y, z, parameters, computed quantities

 The surrogate model replaces the original model with new DNN function that approximate the model in the whole space of parameters

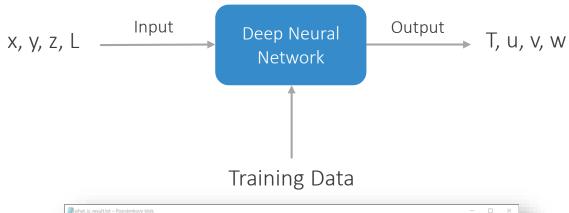


Surrogate Model Workflow



How Training Data look like?

- Inputs and Outputs together
- Data file (*.csv, *.txt, *.dat) or result table



| Soubor Úpravy Form | át Zobrazení Nános | abás | | | | | | | |
|---------------------------|--------------------|-----------------|-----------------|------------------|----------------|-----------------------|----------------------|-------------|--|
| % Model: | | heating box su | ppogato mph | | | | | | |
| % Version: | | 6.2.0.278 | rogace.mpn | | | | | | |
| % Date: | | 2023, 17:43 | | | | | | | |
| % Dimension: | 3 | 2025, 17:45 | | | | | | | |
| % Nodes: | 449088 | | | | | | | | |
| <pre>% Expressions:</pre> | 449088 | | | | | | | | |
| & Description: | | longth Townson | stune Velesitu | field w commo | ant Valasit | field a common of | nt, Velocity field, | | |
| | m m | tength, tempera | acure, verocity | / field, x-compo | ient, verocrty | y field, y-compone | nt, velocity field, | z-component | |
| % Length unit: % x | | z | L (m) | T (degC) | u (m/s) | | w (m/s) | | |
| % x 0.29650 | y 0.013122 | z 0.027793 | 2.0000 | 20.767 | 0.10762 | v (m/s) -9,7499E-5 | -2.4080E-4 | | |
| | | 0.029284 | 2.0000 | | 0.10762 | | | | |
| 0.30000 0.30000 | 0.010443 | | | 20.774 | | -7.0311E-5 | -3.1038E-4 | | |
| | 0.013482 | 0.023753 | 2.0000 | 21.187 | 0.10541 | -2.8649E-4 | -4.0347E-4 | | |
| 0.30000 | 0.017163 | 0.029283 | 2.0000 | 20.468 | 0.10995 | -8.9415E-5 | -1.5154E-4 | | |
| 0.30000 | 0.0064463 | 0.023548 | 2.0000 | 21.705 | 0.10141 | -2.4970E-4 | -5.2141E-4 | | |
| 0.30000 | 0.014000 | 0.035000 | 2.0000 | 20.422 | 0.11040 | -8.0534E-5 | -9.1413E-21 | | |
| 0.29657 | 0.019238 | 0.027594 | 2.0000 | 20.462 | 0.10966 | -8.6854E-5 | -2.1148E-4 | | |
| 0.30000 | 0.018929 | 0.023976 | 2.0000 | 20.743 | 0.10810 | -1.3140E-4 | -3.6234E-4 | | |
| 0.30000 | 0.024509 | 0.028731 | 2.0000 | 20.214 | 0.11132 | -8.2612E-5 | -1.3212E-4 | | |
| 0.30000 | 0.030656 | 0.030470 | 2.0000 | 20.069 | 0.11218 | -2.8149E-5 | -5.8206E-5 | | |
| 0.30000 | 0.028000 | 0.035000 | 2.0000 | 20.075 | 0.11228 | -1.1882E-6 | 2.4723E-21 | | |
| 0.29561 | 0.026111 | 0.029492 | 2.0000 | 20.148 | 0.11169 | -6.4490E-5 | -9.2760E-5 | | |
| 0.30000 | 0.029938 | 0.024539 | 2.0000 | 20.182 | 0.11160 | -4.9194E-5 | -1.2318E-4 | | |
| 0.29551 | 0.030017 | 0.035000 | 2.0000 | 20.050 | 0.11238 | -2.4874E-5 | -1.0750E-18 | | |
| 0.30000 | 0.035000 | 0.035000 | 2.0000 | 20.034 | 0.11242 | -2.0380E-36 | -7.5227E-22 | | |
| 0.30000 | 0.035000 | 0.028000 | 2.0000 | 20.074 | 0.11224 | -1.4805E-21 | -1.0540E-5 | | |
| 0.29411 | 0.030913 | 0.028039 | 2.0000 | 20.091 | 0.11200 | -3.3617E-5 | -7.4633E-5 | | |
| 0.29495 | 0.035000 | 0.030571 | 2.0000 | 20.045 | 0.11237 | -1.1254E-21 | -2.7243E-5 | | |
| 0.29298 | 0.035000 | 0.035000 | 2.0000 | 20.029 | 0.11246 | 8.0112E-20 | 1.1190E-19 | | |
| 0.29480 | 0.022472 | 0.021920 | 2.0000 | 20.636 | 0.10852 | -1.5130E-4 | -2.2188E-4 | | |
| 0.30000 | 0.023795 | 0.020906 | 2.0000 | 20.617 | 0.10913 | -2.5332E-4 | -2.6915E-4 | | |
| 0.29648 | 0.029047 | 0.021346 | 2.0000 | 20.299 | 0.11071 | -9.6794E-5 | -1.6284E-4 | | |
| 0.30000 | 0.029172 | 0.017625 | 2.0000 | 20.448 | 0.11011 | -1.7653E-4 | -2.1646E-4 | | |
| 0.30000 | 0.035000 | 0.021000 | 2.0000 | 20.203 | 0.11170 | -5.0062E-21 | -1.2612E-4 | | |
| 0.29616 | 0.011415 | 0.021595 | 2.0000 | 21.678 | 0.10105 | -2.2105E-4 | -3.8447E-4 | | |
| 0.29625 | 0.023490 | 0.017717 | 2.0000 | 20.869 | 0.10709 | -2.5472E-4 | -2.0056E-4 | | |
| 0.30000 | 0.017150 | 0.017600 | 2.0000 | 21.625 | 0.10208 | -4.6694E-4 | -4.4046E-4 | | |
| 0.30000 | 0.023346 | 0.013986 | 2.0000 | 21.185 | 0.10500 | -4.9536E-4 | -2.3027E-4 | | |
| 0.29327 | 0.026825 | 0.025507 | 2.0000 | 20.231 | 0.11107 | -6.7357E-5 | -1.2716E-4 | | |
| 0.29597 | 0.019467 | 0.014943 | 2.0000 | 21.632 | 0.10179 | -3.8262E-4 | -2.9689E-4 | | |
| 0.30000 | -8.6044E-5 | 0.023351 | 2.0000 | 21.924 | 0.099725 | 1.9102E-5 | -5.6845E-4 | | |
| 20635 | 0 0000000 | 0 000011 | 2 0000 | 22 102 | 0 007011 | Řádek 1, Sloupec 50 | 100 % Windows (CRLF) | UTF-8 | |

How to Generate Training Data?

- Third-party data
 - External data file
- Parametric study results
 - Manual setting of sampling (range)
 - Time-consuming for larger number of parameters
- Surrogate Model Training study
 - Design Of Experiments method generates dataset automatically
 - Default option is Latin Hypercube Sampling (LHS)
 - More strategic approach for larger number of parameters

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|--|--|--|------------------------|---|---------------------|---|
| File Home Definitions Geometry Sketch | Materials Physics Mesh Stu | udy Results Develop | er Colored Selections | | | |
| Builder Manager 1 - Component - | Pi Parameters Pi Parameter Case | Build All Part Libraries | | Add Add • Physics Mathematics | Build Mesh | Compute Stud |
| Workspace Model | Definitions | Geometry | Materials | Physics | Mesh | Study |
| Model Builder + → ↑ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ | Solution to use: Automa Surrogate model: Design Output table group: Design - Quantities of interest (Output * Expression comp1.ppb1 comp1.ppb2 $\uparrow \downarrow + := \ \ e \downarrow \bullet$ * Input Parameters * Parameter r0 (Radial position) * z0 (Axial position) * z0 (Axial position) * E (Activation energy) * ke (Thermal conductivity) * dHrx (Heat of reaction) * Correlation groups Correl + := \ \ e \downarrow * Number of input points type: Number of input points: Random seed type: | ig te and build surrogate mo stic of experiments (No surrog of Experime | r + • ∎ • odel • | x y Messages € 0 20 0.032140 0.33178 0.025539 0.60275 0.021120 0.381781 0.025539 0.60275 0.021120 0.98724 | 850 e-3 0.85 | Design Data × Comp1.ppb1 cor 331.64 0.51 314.94 0.31 319.27 0.18 337.06 0.71 |

Deep Neural Network Settings

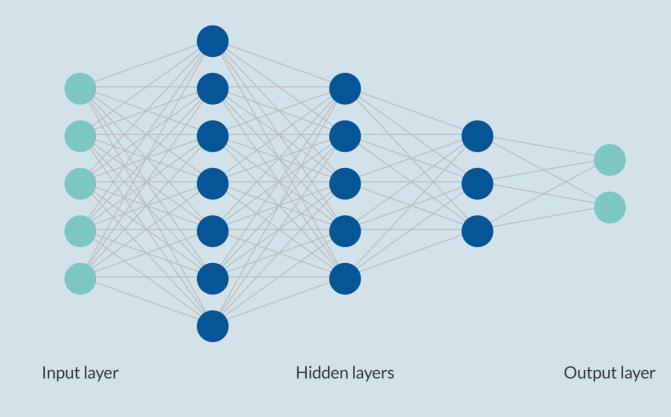
- 1. Training data source
- 2. Data source column settings
 - Inputs: arguments
 - Outputs: function value
- 3. Deep Neural Network settings
 - Number of layers
 - Output features (neurons) per layer
 - Activation function
- 4. Training and Validation settings
- 5. Training / Continue training

| | Settings C C | | | | | | | | |
|------------------------------|--|---------|-----------------------|--|---|--|--|--|--|
| | 🎯 Plot 🐻 Create Plot 🔯 Train Model 🛗 Continue Training | | | | | | | | |
| | ▼ Layers | | | | | | | | |
| | ₩ Туре | | Settings | | | | | | |
| | Dense | • | Input, Input features | =1, Output features=1, Activation=tanh | | | | | |
| | Dense | • | Hidden, Output feat | | | | | | |
| 3. Deep Neural Network — | Dense | • | Hidden, Output feat | ures=15, Activation=tanh | | | | | |
| | Dense | • | Hidden, Output feat | ures=15, Activation=tanh | | | | | |
| | Dense | • | Output, Output feat | ures=1, Activation=Linear (none) | | | | | |
| | | | | | | | | | |
| | ↑ ↓ + ≣ ∖ | | | | | | | | |
| | Output features: 1 | | | | | | | | |
| | Activation: tank | h | | | • | | | | |
| | ▼ Data | | | | | | | | |
| | | | | | | | | | |
| 1. Training data source —— | | | | | | | | | |
| | | | | | | | | | |
| | ☑ Ignore NaN/Inf data points | | | | | | | | |
| | Data Column Settin | ngs | | | | | | | |
| | * Columns | Туре | | Settings | | | | | |
| 2. Inputs and Outputs | L (m) | Argu | ument 🔹 | Name=x1, Scaling=to01, Unit=m | | | | | |
| | Wire surface temperatur | re Fund | ction values 🔹 | Name=dnn1, Scaling=to01, Unit=K | | | | | |
| | Training and Valida | ation | | | | | | | |
| | Method: | Adam | | | • | | | | |
| | Learning rate: | 1e-3 | | | | | | | |
| | Weight decay: | 0 | | | | | | | |
| | Batch size: | 512 | | | | | | | |
| | Loss function: | | an-square error | • | | | | | |
| | Random seed type: | Fixed | | • | | | | | |
| 4. Training and Validation — | Random seed: | 0 | | | | | | | |
| | - Stop condition | | | | | | | | |
| | Number of epochs: | 10000 | | | | | | | |
| | - Validation data | | | | | | | | |
| | Validation data: | Random | sample of data value | S | • | | | | |
| | Validation data fraction: | 0.2 | | | | | | | |
| | Random seed type: | Fixed | | | • | | | | |
| | Random seed: | 0 | | | | | | | |

5. Start of training, Continue training

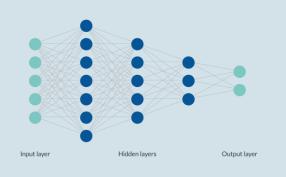
Deep Neural Network

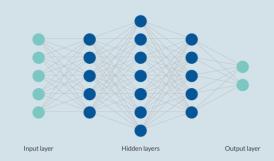
- A DNN model consists of an input layer, a series of hidden layers, and an output layer.
- Each layer consists of a number of nodes, or neurons, or output features. The figure shows a graph for a network with three hidden layers, 5 input nodes, and 2 output nodes.
- You can define any number of layers and nodes for a DNN surrogate model.

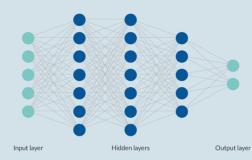


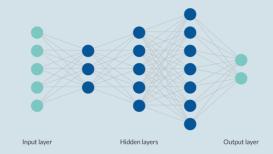
Optimizing Neural Network Architecture

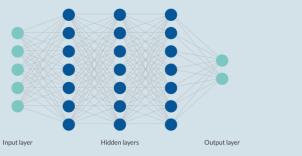
- Selection of layers and nodes is iterative and based on:
 - Problem-specific knowledge
 - Empirical testing







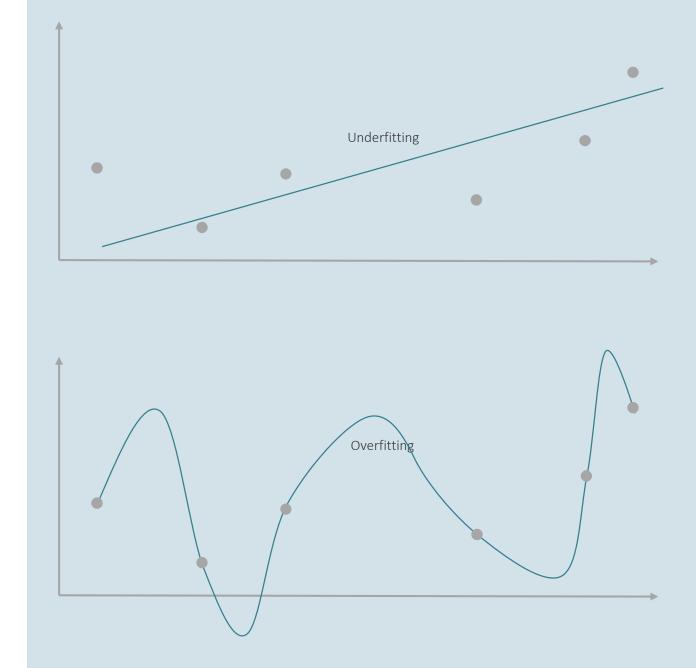






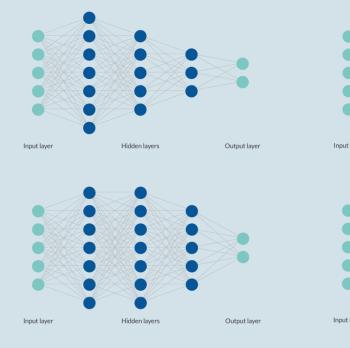
Optimizing Neural Network Architecture

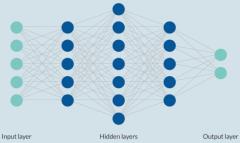
- Selection of layers and nodes is iterative and based on:
 - Problem-specific knowledge
 - Empirical testing
- Balance is key:
 - Too few layers/nodes may lead to underfitting and be inadequate for complex surrogate modeling.
 - Excess layers/nodes can cause overfitting, yielding high accuracy on training data but poor generalization.



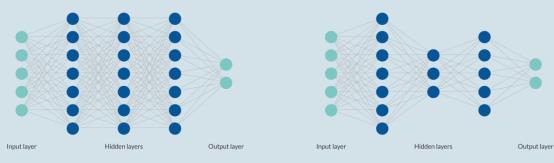
Optimizing Neural Network Architecture

- Selection of layers and nodes is iterative and based on:
 - Problem-specific knowledge
 - Empirical testing
- Balance is key:
 - Too few layers/nodes may lead to underfitting and be inadequate for complex surrogate modeling.
 - Excess layers/nodes can cause overfitting, yielding high accuracy on training data but poor generalization.
- Consider computational costs:
 - More layers/nodes increase model evaluation time.
 - Rule-of-thumb starting point: 3 hidden layers with
 64, 32, and 16 nodes



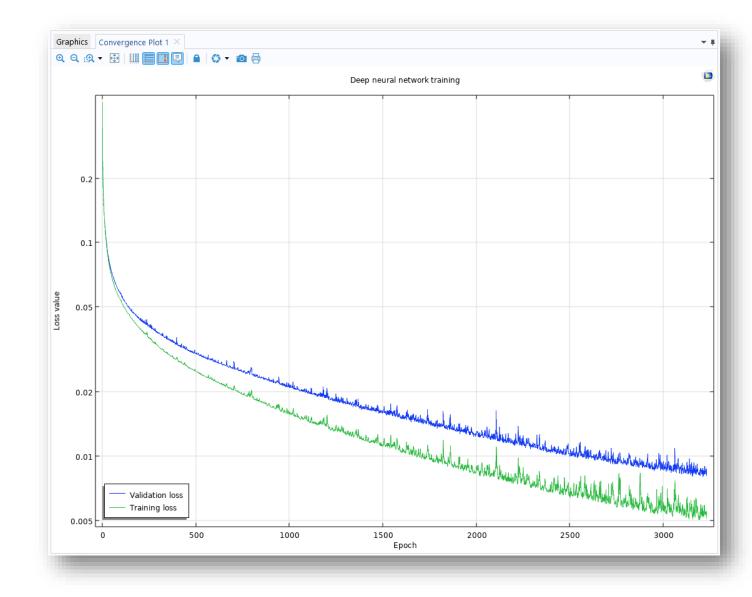






Training a DNN

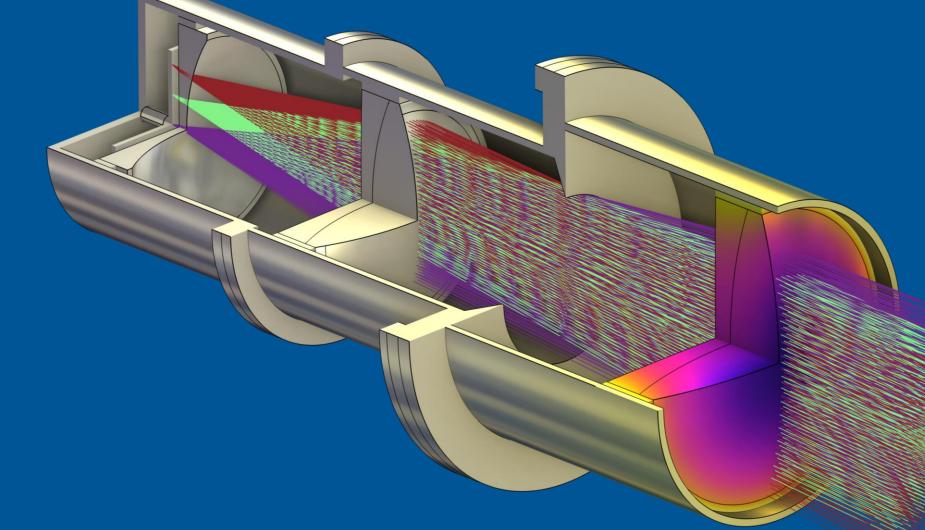
- The internal parameters of the neural network are called weights and biases
- Training involves optimizing weights and biases to minimize error
- Objective of training: Align surrogate model closely with the finite element model
- Error measurement is done via the loss function
- Default loss function is root mean squared error (RMSE)



Training and Validation Settings

- The DNN is trained using a specialized optimization solver.
- The solver settings are called hyperparameters. Some of the most important are:
 - Learning rate:
 - Controls optimization step size
 - Analogous to numerical damping in nonlinear solvers
 - Batch size:
 - Determines subdivision of training data into subsets
 - *– Number of epochs:*
 - Indicates total passes through the full dataset

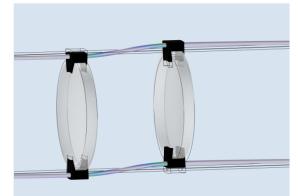
| Training and Valida | tion | |
|---|--------------------------------|---|
| Method: | Adam | |
| Learning rate: | 1e-3 | |
| Weight decay: | 0 | |
| Batch size: | 512 | |
| Loss function: | Root-mean-square error | |
| Random seed type: | Fixed • | |
| Random seed: | 0 | |
| Stop condition | | |
| Number of epochs: | 10000 | |
| Validation data | | |
| Validation data: | Random sample of data values 🔹 | |
| Validation data fraction: | 0.2 | |
| Random seed type: | Fixed • | |
| Random seed: | 0 | ~ |
| | | |

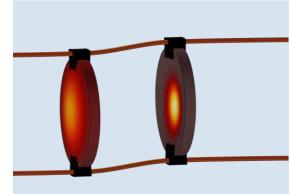


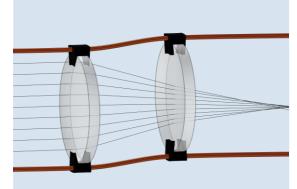
STOP Analysis

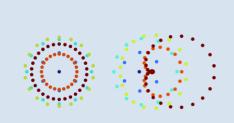
Tomáš Vrbata

STOP Analysis in COMSOL®









Structural

Model the structural displacements in an optical system.

Thermal

Apply a fixed operating temperature or simulate the temperature distribution. Heat sources may include absorption from the beam itself.

Optical

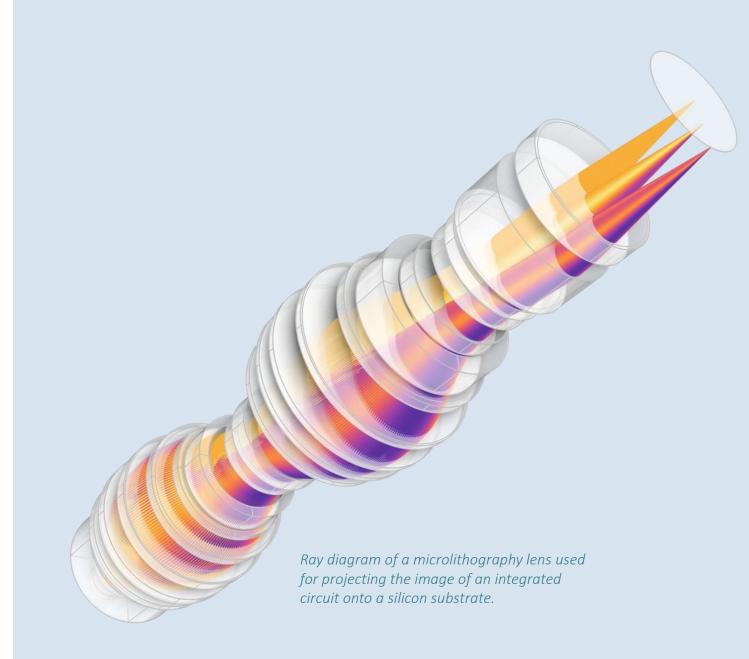
With the local temperature and displacement considered, model how light will propagate through the system.

Performance

Evaluate the optical performance under the influence of thermal and structural loads.

OVERVIEW Geometrical Optics

- Ray tracing in homogeneous and graded media
- Detailed analysis of ray intensity and polarization
- Variety of features for releasing rays and controlling interaction with boundaries
- Functionality for multiscale electromagnetics modeling
- Multiphysics couplings for STOP analysis



Ray Optics Module Part Library

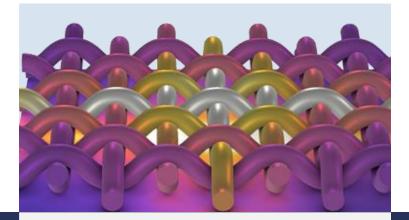
The Ray Optics Module Part Library contains parameterized geometry parts for optical systems:

- Apertures and obstructions
- Aspheric, cylindrical, doublet, triplet, and spherical lenses
- Beam splitters and prisms
- Mirrors and reflectors

The parts include predefined selections for convenient set up of boundary conditions

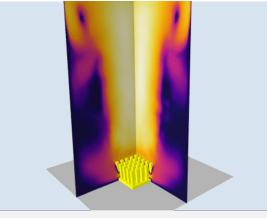
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| A 📑 🖬 🛞 | Pi | a = Variables | | Variable Utilities | N | 📑 Imp | eLink + | | × | ÌÌÌ | | = | ~ 0 | 1 |
| pplication Model Component Add | Parameters | | | | Build | LIVE | Add | Geometrical | Add | Build | | Compute | study | |
| Builder Manager 1 + Component + | • | Pi Paramete | | | All | | Materia | | Physics | Mesh | 1• | | 1. | - 5 |
| Workspace Model | | Def | initions | | Geo | metry | / Materia | s Physics | ; | Me | sh | | Study | |
| /odel Builder | Setting | IS | | | - | | Graphics | | | | | | | |
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| double_gauss_lens.mph (root) | | elected 🔻 🔋 | Build All (|)biects 💷 | | | | ÷ 🖬 🗸 - L | - <u>-</u> | | | | - | |
| Global Definitions | | herical Lens 3 | | objects 🏢 | - = | | | | | | | | | |
| Pi Parameters 1: Lens Prescription | | | | | ▼ 1 | | | | | | - | | | |
| Pi Parameters 2: General | Choose f | rom Library | | | | | | | - | \neg | | | | - |
| Geometry Parts | Input P | arameters | | | | | | | | | | | | |
| Inputs | | | | | | | | // | | | - | T | | - |
| (ii) Materials | Name | Expression | n | Value | Description | | | // | | / / | | / | - | 1 |
| Image: Component 1 (comp 1) Image: Image: Component 1 (comp 1) Image: Image: Component 1 (comp 1) Image: Comp 1) Image: Component 1 (comp 1) Image: Comp 1) Image | R1 | R1_3 | | 0 m | Radius of cu | | 11 | | | / / | | / | | |
| Definitions Isoundary System 1 (sys1) | R2 | R2_3 | | 25.65 mm | Radius of cu | | 11 | | | / / | / | | | |
| View 1 | Tc | Tc_3 | | 2 mm | Center thick | | // | | 1 | | / | | | |
| Camera | d0 | d0_3 | | 51 mm | Lens full dia | | // | | 1 | | / | | | |
| Directional Light 1 | d1 | d1_3 | | 0 m | Diameter, su | | // | | | { | / | | | |
| 🚛 Directional Light 2 | d2 | d2 3 | | 40 mm | Diameter, su | | // | | 1 | | 1 | | | 1 |
| Directional Light 3 | | | | 40 mm | | | // | | | 1 | / | | | 1 |
| 🐥 Headlight 4 | d1_clear | d1_clear_3 | | | Clear apertu | | // | | | | / | | | |
| Clip Plane 1 | d2_clear | d2_clear_3 | | 39 mm | Clear apertu | | 11 | | | 11 | | | | |
| Double Gauss Lens Lens 1 (pi1) | nix | 0 | | 0 | Local optica | | 11 | | 1 | 1 | | | | |
| Lens 1 (pt) | niy | 0 | | 0 | Local optica | | | | | | | Y | | |
| Lens 3 (pi3) | niz | 1 | | 1 | Local optica | | | | 1 | 1 | | | F A | |
| Stop (pi4) | n_extra_r | 0 | | 0 | Number of (| | | | | f | | | H | |
| └ <mark>☆</mark> Lens 4 (<i>pi5</i>) | n_extra_a | 0 | | 0 | Number of (| | 1 | | 1 | ľ | | | | |
| 😽 Lens 5 (pi6) | | | | | > | | 11 | | | l | | | | |
| 🤧 Lens 6 (<i>pi7</i>) | > | . • | | | | | // | | | l. | | | | 1 |
| by Image (<i>pi8</i>) | | | | | | | // | | | | | | | 1 |
| Form Union (fin) Cumulative Selections | Positio | n and Orien | tation of O | utput | | | // | | 1 | | | | | |
| Cumulative Selections | — Coordina | te system in | part | | | | // | | | | | | | |
| Geometrical Optics (gop) | Work plane | | • | | - | | // | | | | | | | 1 |
| Mesh 1 | | | xy-plane | | • E1 | | | | | | | | | |
| ▷ 🐭 Study 1 | — Coordina | ite system to | match | | | | | | 1 | | 1 | | | |
| A 📠 Results | Take work p | lane from: | Lens 2 (pi | 2) | ▼ 1 | | // | | | | | | | |
| Datasets | Work plane | : | Surface 2 | ertex intersec | ▼ = 1 | | 11 | | 1 | | | | | |
| Views 885 Desired Veluce | | | Landeer | and a measure | | | | | 1 | | | | | |
| 8년 Derived Values 王 Tables | — Displacer | | • | | | | | 11 | 1 | | 1 | | - | ſ |
| Ray Diagram 1 | xw: | | 0 | | mm | | | | | | | 7 | | - |
| Ray Diagram 2 | yw: | | 0 | | mm | | У | | 1 | | | | | |
| Spot Diagram | zw: | | T_2 | | mm | | X - T - | | | \backslash | | | | |
| Optical Aberration Diagram | - Rotation | | | | | | 2 | | | | | | | |
| Optical Aberration 1 | Specify: | | Axis of rot | ation | • | | | | 1 | -1 | | | | |
| Optical Aberration 2 | | | | | | | | | | ~ | | | | |
| 隨 Export | Axis type: | | zw-axis | | | | Messages \times | Progress Log | | | | | | |

OVERVIEW Heat Transfer Functionality



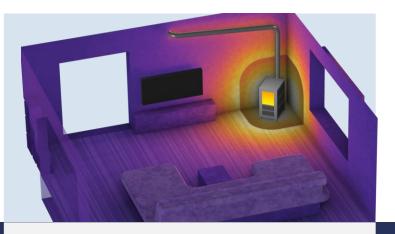
Conduction

- Isotropic, anisotropic, linear, and nonlinear thermal conductivity
- Thermal contact
- Thin layers



Convection

- Free and forced convection
- Laminar and turbulent flow
- Effective material properties



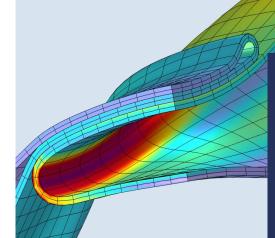
Radiation

- Surface-to-ambient and surface-to-surface radiation
- External radiation sources
- Radiation in participating media

OVERVIEW Structural Mechanics Functionality

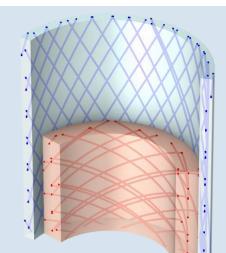


Combine solids, single and layered shells, plates, membranes, beams, pipes, trusses, and wires.



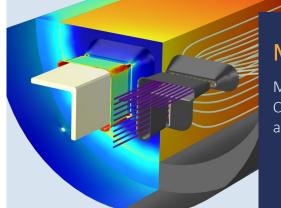
Analysis Types

Run stationary, transient, and frequency response analyses, as well as specialized analyses such as mechanical contact, buckling, and fatigue.



Material Models

Choose from a wide variety of elastic, viscoelastic, hyperelastic, elastoplastic, and composite material models. Materials can be spatially varying, anisotropic, and dependent on other variables.



Multiphysics

Multiphysics couplings with heat transfer, CFD, acoustics, electromagnetics, optics, and more are available.

Study Setup

One-Way Coupled STOP Analysis

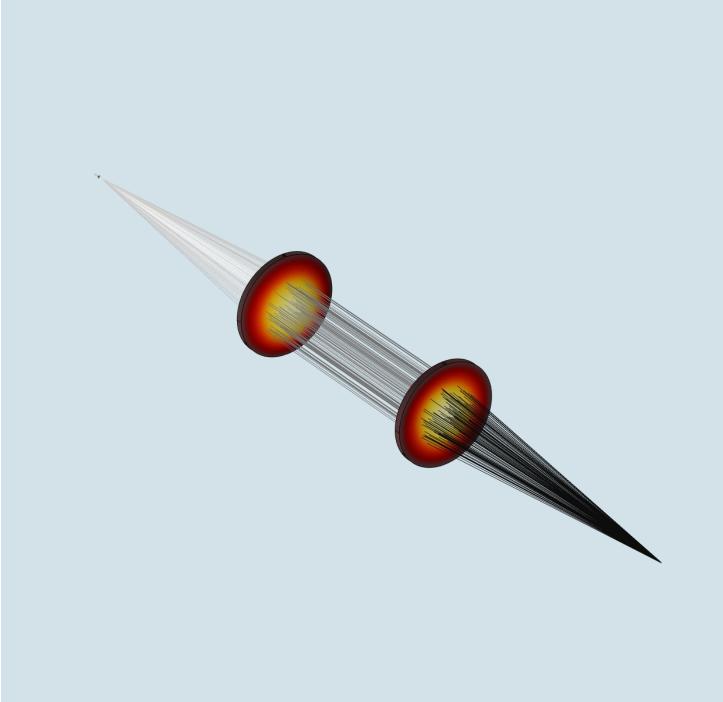
- With the temperatures affecting the deformations, and both temperatures and deformations influencing the ray paths, you can solve for the different physics interfaces one at a time.
 - Component 1 (comp 1)
 Definitions
 Geometry 1
 Materials
 Meterials
 Geometrical Optics (gop)
 Heat Transfer in Solids (ht)
 Solid Mechanics (solid)
 Multiphysics
 Mesh 1
 Step 1: Heat Transfer in Solids
 Step 2: Solid Mechanics
 Step 3: Geometrical Optics
 Solver Configurations
 Job Configurations

STOP Analysis with Ray Heating

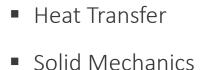
- The dedicated *Bidirectionally Coupled Ray Tracing* study type, along with the *Ray Heat Source* feature, will automatically follow the iteration scheme in the previous slide.
- A Component 1 (comp 1) Definitions A Geometry 1 Þ Materials Geometrical Optics (gop) Heat Transfer in Solids (ht) 🖶 Solid Mechanics (solid) ⊳ Multiphysics Mesh 1 🔺 🗞 Study 1 Parametric Sweep Step 1: Bidirectionally Coupled Ray Tracing Solver Configurations Job Configurations

DEMO: Surrogate model for STOP Analysis

Creation of a digital twin of Laser
 Focusing System to obtain
 instantaneous values of temperature,
 stress and lens deformation.

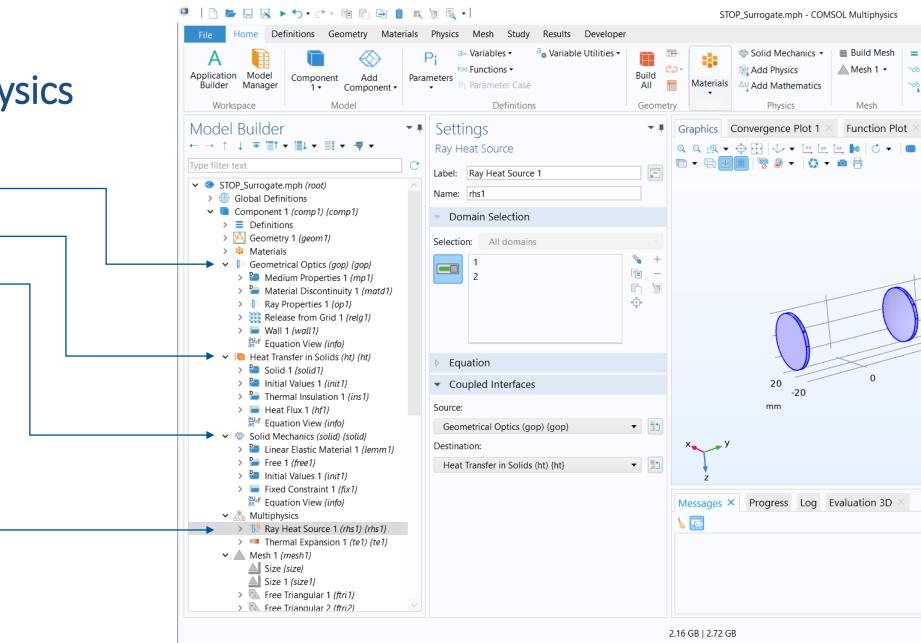


COMSOL Multiphysics



Geometrical Optics

 Ray Heat Source Thermal Expansion

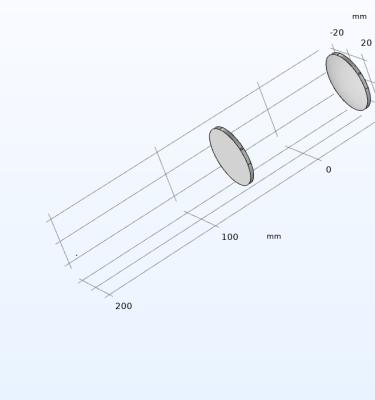


Our Neural Networks for STOP Model

- 6 DNNs in total (3 for each lens)
- 6 input parameters: x, y, z, lrms, TO, lam*
- Output parameters: temperature, stress, displacement
- Training data for 300 parameter combinations (Irms, TO, Iam)
- 4 hidden layers, number of neurons: 100, 50, 30, 10
- Activations:
 - Output layers activation: linear
 - Other layers activation: tanh

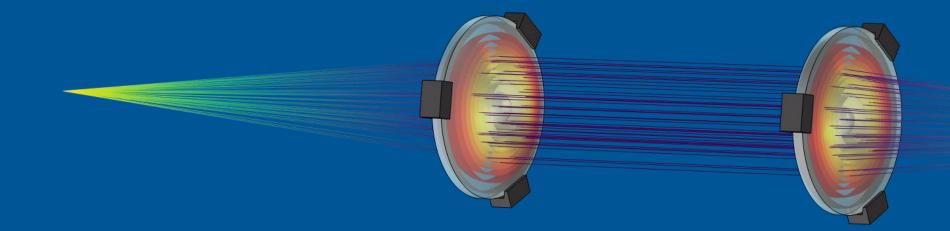
| Settings | | | - # | | | | |
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| Deep Neural | Networ | k | | | | | |
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| Label: DNN_T | 1 | | | | | | |
| Layers | | | | | | | |
| ▶ Туре | Set | tings | | | | | |
| Dense | | 2 | features=6, Output features=100, Activation=tanh | | | | |
| Dense | | | tput features=100, Activation=tanh | | | | |
| Dense | ▼ Hid | den, Ou | tput features=50, Activation=tanh | | | | |
| Dense | ▼ Hid | den, Ou | tput features=30, Activation=tanh | | | | |
| Dense | ▼ Hid | den, Ou | tput features=10, Activation=tanh | | | | |
| Dense | ▼ Out | put, Out | put features=1, Activation=Linear (none) | | | | |
| | | | | | | | |
| $\uparrow \downarrow + \equiv$ | 6 | | | | | | |
| > Data | | | | | | | |
| Data Colu | mn Setti | nas | | | | | |
| | | 5 | | | | | |
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| Column 2 | Argur | men 🔻 | Name=x2, Scaling=to01, Unit=mm | | | | |
| Column 3 | | men 🔻 | Name=x3, Scaling=to01, Unit=mm | | | | |
| Column 4 | | men 🔻 | Name=x4, Scaling=to01, Unit=W | | | | |
| Column 5 | | men 🔻 | Name=x5, Scaling=to01, Unit=K | | | | |
| Column 6 | Argur | | Name=x6, Scaling=to01, Unit=mm | | | | |
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| Training ar | nd Valida | ation | | | | | |
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Progress Log Evaluation 3D

* Lrms = laser power, TO = room temperature, Iam = laser wavelength



How to Create Surrogate Model from STOP Simulation

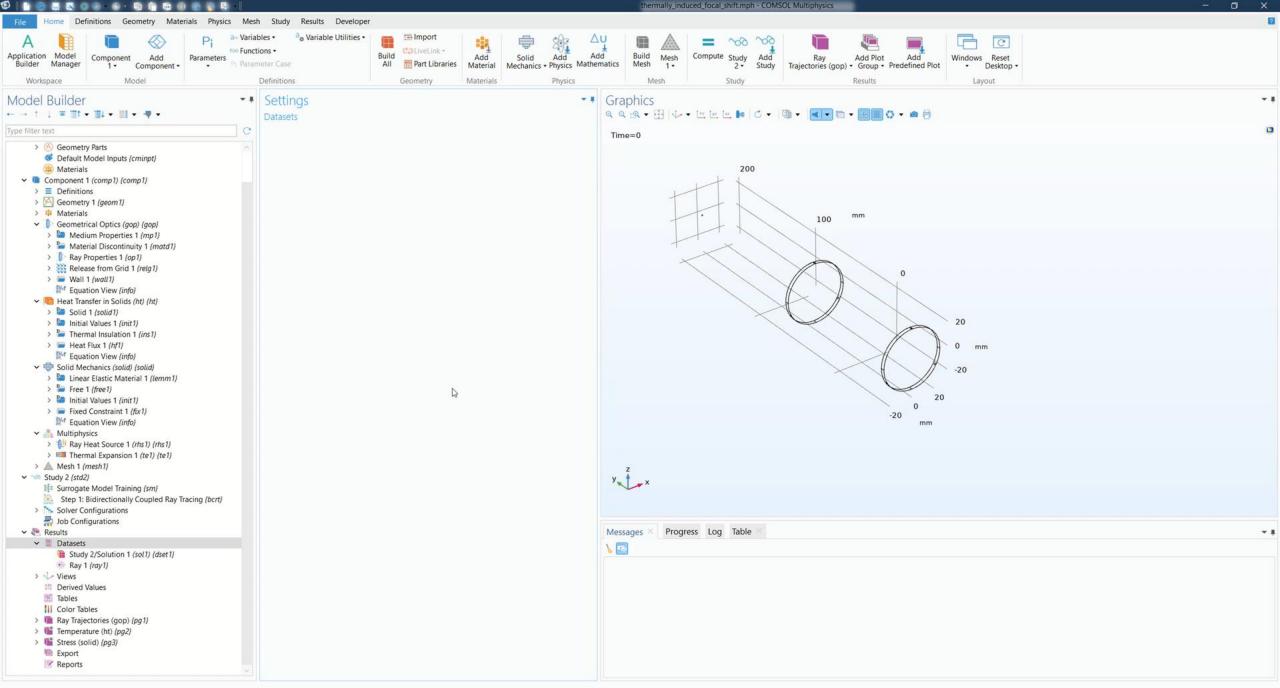
Tomáš Vrbata

Setting up Surrogate Model Training

thermally_induced_focal_shift.mph - COMSOL Multiphysics Definitions Geometry Materials Physics Mesh Study Results Developer 2 Import a= Variables • a Variable Utilities • Δu P: 00 000 C = roo Functions • CDLiveLink -Compute Study Application Model Builder Manager Build Add Build Mesh Add Plot Component Add Parameters Add Geometrical Add Add Ray Add Windows Reset All Part Libraries Physics Mathematics Mesh 1. Component • Material Optics -1. 1. Study Trajectories (gop) - Group - Predefined Plot Desktop • . Model Definitions Materials Physics Mesh Study Results Workspace Geometry Layout Model Builder Settings **• •** Graphics - -+ → ↑ ↓ ■ "`` + "↓ + || + ♥ + Study C = Compute C Update Solution 0 Irms(2)=3000 W Time=1.3976E-9 s Ray trajectories Surface: Temperature (K) ✓ ♦ thermally_induced_focal_shift.mph (root) Label: Study 1 E ĸ ✓ ⊕ Global Definitions ▲ 504 200 Pi Parameters 1 (default) Study Settings > (A) Geometry Parts Generate default plots Of Default Model Inputs (cminpt) 500 Generate convergence plots Materials Component 1 (comp1) (comp1) Store solution for all intermediate study steps 100 > Definitions Generate default plots for intermediately stored solutions > Seometry 1 (geom1) 490 Plot the location of undefined values > 🌐 Materials mm ✓ ● Geometrical Optics (gop) (gop) Information > Dedium Properties 1 (mp1) 0 > San Material Discontinuity 1 (matd1) 480 Last computation time: > Properties 1 (op1) 2 min 43 s > 3 Release from Grid 1 (relg1) Last computation date: > Wall 1 (wall 1) 470 # Equation View (info) Sep 30, 2023, 2:48:12 AM -100 Heat Transfer in Solids (ht) (ht) Computed in version: > Solid 1 (solid1) COMSOL 6.2.0.259 > 🛅 Initial Values 1 (init 1) 460 > Thermal Insulation 1 (ins 1) > 🔚 Heat Flux 1 (hf1) Equation View (info) -200 Solid Mechanics (solid) (solid) 450 20 > Einear Elastic Material 1 (lemm1) 2 > 🎥 Free 1 (free 1) > Initial Values 1 (init1) 0 mm > Fixed Constraint 1 (fix1) 440 HI Equation View (info) -20 ✓ ▲ Multiphysics > 1 Ray Heat Source 1 (rhs1) (rhs1) y x > I Thermal Expansion 1 (te1) (te1) 20 ▼ 431 > A Mesh 1 (mesh1) 0 ✓ ™ Study 1 (std1) -20 Parametric Sweep (param) Progress Log Table X Step 1: Bidirectionally Coupled Ray Tracing (bcrt) Messages - I > Solver Configurations 10 > 🛃 Job Configurations ✓ ♣ Results > Datasets > 🔶 Views 10 Derived Values Tables III Color Tables > in Ray Trajectories (gop) (pg1) > Temperature (ht) (pg2) > I Stress (solid) {pg3} > Deposited Ray Power (lenses) (pg4)

S I Donacitad Pau Dowar (taraat) /na51

Generation of training data



Setting up a Deep Neural Network

thermally_induced_focal_shift1.mph - COMSOL Multiphysics Definitions 2 Geometry Materials Physics Mesh Study Results Developer a= Variables • a Variable Utilities • - Import Δu P: = 00 00 roo Functions • CDLiveLink -Application Model Builder Manager Compute Study Build Build Add Mesh Add Plot Component Add Parameters Add Geometrical Add Add Ray Add Windows Reset Manager All Part Libraries Physics Mathematics Mesh 1. Component -Material Optics -1. 2+ Study Trajectories (gop) . Group . Predefined Plot Desktop • . Model Definitions Geometry Materials Physics Mesh Study Results Layout Workspace Model Builder ▼ ■ Settings ▼ ♣ Graphics Function Plot * # + → ↑ ↓ ■ "`` + "↓ + || + ♥ + QQQ+HU+EEE0C+ 0+ 4+ 0000+ 0 Surrogate Model Training C = Compute C Update Solution Time=1.401E-9 s Ray trajectories > A Geometry 1 (geom1) Label: Surrogate Model Training E ×10¹⁷ > 🕸 Materials ✓ ● Geometrical Optics (gop) (gop) Study Settings + • *** > Medium Properties 1 (mp1) > San Material Discontinuity 1 (matd1) Compute action: Compute and build surrogate model . > Ray Properties 1 (op1) Automatic Solution to use: • > 3 Release from Grid 1 {relg1} > Wall 1 (wall 1) Design of experiments (No surrogate model) Surrogate model: -20 HI Equation View (info) - 55 Output table group: Design of Experiments (de1) Heat Transfer in Solids (ht) (ht) mm > Solid 1 (solid1) Quantities of interest (Outputs) > a Initial Values 1 (init 1) + Expression > Thermal Insulation 1 (ins1) Description Individual solution to use -20 > 🐱 Heat Flux 1 (hf1) 1 From "Solution to use" . Equation View (info) Solid Mechanics (solid) (solid) 200 3 > 😓 Linear Elastic Material 1 (lemm1) > 🎥 Free 1 (free1) > Initial Values 1 (init1) 100 1 1 + = \ + * > Fixed Constraint 1 (fix1) Equation View (info) Input Parameters ✓ [™] Multiphysics 0 + Parameter > 1 Ray Heat Source 1 (rhs1) (rhs1) Source type Parameter description > I Thermal Expansion 1 (te1) {te1} mm Analytic • Uniform from [1000, 4000] Irms (Roo! 🔻 > A Mesh 1 (mesh1) -100 Study 2 (std2) Analytic Uniform from [-20, 50] T0 (Room • Surrogate Model Training (sm) Analytic • Uniform from [800, 2000] lam (Fiber 🔻 Step 1: Bidirectionally Coupled Ray Tracing (bcrt1) 20 > 🐆 Solver Configurations 0 1 1 + 1 -200 -20 > 🛃 Job Configurations Correlation groups Correlation matrix mm ✓ 🥐 Results Active У., > Datasets + = \ # > 🕹 Views Input parameters sampling settings 10 Derived Values Number of input points type: Manual > III Tables ٠ Messages × Progress Log Design Data Color Tables - 1 300 Number of input points: > 🐚 Ray Trajectories (gop) (pg1) > 🎬 Temperature (ht) (pg2) Random seed type: Automatic . > 🎬 Stress (solid) {pg3} 1014 Initial random seed: > 1 Displacement (solid) (pg4) > 1 Ray Trajectories (gop) 1 (pg5) Advanced Settings > Temperature (ht) 1 (pg6) > 1 Stress (solid) 1 (pg7) Accumulated probe table > 🌃 Ray Trajectories (gop) 2 (pg8) Output table: New > Temperature (ht) 2 (pa9) Use all probes > 🌃 Stress (solid) 2 (pg10) > 🐚 Export Error handling: Skip problematic parameters ٠ Reports Keep model evaluations in memory: Only last .

DNN visualization and postprocessing

thermally_induced_focal_shift1.mph - COMSOL Multiphysics 2 Definitions Geometry Materials Physics Mesh Study Results Developer a= Variables • a Variable Utilities • Import Δu P: 00 00 : = CDLiveLink roo Functions • Compute Study Build Build Application Model Add Mesh Component Add Parameters Add Geometrical Add Add Ray Add Plot Add Windows Reset Builder Manager All Part Libraries Physics Mathematics Mesh Component · Material Optics -1. 2. Study Trajectories (gop) . Group . Predefined Plot Desktop • 1 -. Model Definitions Materials Mesh Results Workspace Geometry Physics Study Layout Model Builder ▼ ■ Settings ▼ I Graphics Convergence Plot 1 Function Plot × - I ← → ↑ ↓ = "↑ • "↓ • || • ♥ • A 0 - 0 A Deep Neural Network 🕐 🖉 Plot 🐻 Create Plot 🔤 Train Model 🔛 Continue Training dnn_T1(x1,x2,x3,2497.2,288.17,0.0014003) (K) thermally_induced_focal_shift1.mph (root) Column 7 Function v Name=dnn_T1, Scaling=to01, Unit=K 🗸 🌐 Global Definitions 20 Column 8 Ignored cr 💌 -52 P Parameters 1 (default) 10 Column 9 Ignored ct 🔻 . DNN_T1 (dnn_T1) {dnn1} mm 420 . DNN_T2 (dnn_T2) (dnn2) Name: dnn_T1 -10 DNN_S1 (dnn_S1) (dnn3) . DNN_S2 (dnn_S2) {dnn4} -20 415 Description: -58 . DNN_D1 (dnn_D1) (dnn5) Scaling: Scale to [0,1] . DNN D2 (dnn D2) (dnn6) > 🛞 Geometry Parts K 410 Unit: Default Model Inputs (cminpt) 20 A Materials Training and Validation 405 Component 1 (comp1) (comp1) Method: Adam > Definitions > A Geometry 1 (geom 1) 0.5e-3 Learning rate: 400 > 🌼 Materials 0 Weight decay: ✓ ● Geometrical Optics (gop) {gop} 0 mm > Medium Properties 1 (mp1) 1024 Batch size: 395 > Salarial Discontinuity 1 (matd1) Loss function: Root-mean-square error . > D Ray Properties 1 (op1) > 33 Release from Grid 1 /rela1} Random seed type: Fixed 390 • > 🚍 Wall 1 (wall1) 0 Equation View (info) Random seed: -20 ✓ 10 Heat Transfer in Solids (ht) {ht} 385 Stop condition > Solid 1 (solid1) Number of epochs: 1000 > 🛅 Initial Values 1 (init 1) > Thermal Insulation 1 (ins1) Validation data 380 > Heat Flux 1 (hf1) Validation data: Random sample of data values -HI Equation View (info) Validation data fraction: 0.1 375 Solid Mechanics (solid) (solid) > En Linear Elastic Material 1 (lemm1) y 1 _ x -Fixed Random seed type: > P Free 1 (free 1) Random seed: 0 > 😓 Initial Values 1 (init1) > Fixed Constraint 1 (fix1) Plot Parameters HI Equation View (info) Messages × Progress Log Design Data * # ✓ [™] Multiphysics Function name: dnn_T1 > 1 Ray Heat Source 1 (rhs1) (rhs1) > I Thermal Expansion 1 (te1) {te1} Plot Argument Lower limit Upper limit Fixed value Unit > A Mesh 1 (mesh1) 🗹 x1 -25[mm] 25(mm) 0[mm] m Study 2 (std2) 🗹 x2 Surrogate Model Training (sm) -59.3029[mm] -51.603[mm] -55.453[mm] m Step 1: Bidirectionally Coupled Ray Tracing (bcrt1) \square x3 -25[mm] 25[mm] 0[mm] m > 🐆 Solver Configurations x4 1001.18 3993.15 2497.16 W > 🛃 Job Configurations 323.061 K x5 253.281 288.171 ✓ ♣ Results x6 8.01119E-4[mm] 0.0019995[mm] 0.00140031[m... m > III Datasets > Views Information 11 Derived Values A He Tablac Trained functions: dnn T1 [K]

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